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–Covers the course well. –Has chapters on "Computer vision" and "Vision based control". –Uses the same notation as we will use in the lectures. L. Sciavicco and B. Siciliano: Modelling and Control of Robot Manipulators (2nd edition)

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what you write down should be your own work, not copied from a peer or a solution manual. Written Problems (30 points) The first set of problems are written, including two from the textbook, Robot Modeling and Control by Spong, Hutchinson, and Vidyasagar (SHV). Please follow the extra clarifications and instructions when provided.